



From Mutually Non-Blocking to Switched Non-Blocking DES

Michael Canu, Naly Rakoto-Ravalontsalama

► To cite this version:

Michael Canu, Naly Rakoto-Ravalontsalama. From Mutually Non-Blocking to Switched Non-Blocking DES. MSR 2013 - Modélisation des Systèmes Réactifs, 2013, Rennes, France. hal-00876645

HAL Id: hal-00876645

<https://inria.hal.science/hal-00876645>

Submitted on 25 Oct 2013

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

From Mutually Non-Blocking to Switched Non-Blocking DES

Michael Canu¹, Naly Rakoto-Ravalontsalama²

1. Ecole des Mines de Nantes, and Univ. los Andes Bogota,
France, Colombia
mcanu@mines-nantes.fr

2. Ecole des Mines de Nantes and IRCCyN
France
rakoto@mines-nantes.fr

RÉSUMÉ. La propriété de système à événements discrets mutuellement non-bloquants a été introduite par Fabian and Kumar (1997). Dans ce papier, nous proposons une extension de cette propriété de 2 à 3 éléments. Nous donnons ensuite une définition de système non-bloquant par commutations, et nous montrons que la propriété "mutuellement non-bloquant" est incluse dans celle de "non-bloquant par commutations". Nous illustrons ce résultat à travers un exemple de système de conversion de protocole, dans lequel le protocole commute entre deux spécifications.

ABSTRACT. The mutually non-blocking property of discrete-event systems has been introduced by Fabian and Kumar (1997). In this paper, we extend the property of mutually non-blocking from 2 to 3 elements. We also propose a definition of switched non-blocking system, and we show the mutually non-blocking property is included in the switched non-blocking property. We illustrate the result with an example of protocol conversion with switched specification.

MOTS-CLÉS : Systèmes à événements discrets; non-blocage mutuel; non-blocage par commutations.

KEYWORDS: Discrete-event systems; mutually non-blocking; switched non-blocking.

1. Introduction

Supervisory control initiated by Ramadge and Wonham (Ramadge and Wonham, 1987) provides a systematic approach for the control of discrete event system (DES) plant. There has been a considerable work in the DES community since this seminal paper. On the other hand, from the domain of continuous-time system, hybrid and switched systems have received a growing interests (Liberzon, 2003). The notion of

switching is an important feature that has to be taken into account, not only in the continuous-time domain but for the DES area too.

In a communication system, a protocol mismatch occurs when the sending and receiving parts use different protocols. A converter is introduced to correct the mismatch between the two different protocols. Correcting means removing by disabling undesirable traces. The example is taken from (Fabian and Kumar, 1997). A survey on the different approaches of communication conversion can be found in (Roop et al., 2009).

As for non-blocking property, there exist different approaches. The first one is the non-blocking property defined in (Ramadge and Wonham, 1987). Since then other types of non-blocking have been defined. The mutually non-blocking property has been proposed in (Fabian and Kumar, 1997) and (Fabian and Kumar, 2000). Other approaches of mutually and globally nonblocking supervision with application to switching control is proposed in (Kumar et al., 2005). Robust non-blocking supervisory control has been proposed in (Bourdon et al., 2005). Other types of non-blocking include the generalised non-blocking property studied in (Malik and Leduc, 2008). Finally discrete-event modeling with switching max-plus systems is proposed in (van den Boom and de Schutter, 2006) while an example of mode switching DES is described in (Faraut-et-al., 2009).

2. Main Results

In this paper, we propose an extension of the mutually non-blocking property, from 2 elements to 3 elements and a definition of switched non-blocking property.

The extension of the mutually non-blocking property from 2 to 3 elements is quite straightforward, since we say that 3 elements (or languages) are mutually non-blocking if they are pairwise mutually non-blocking.

We propose then a definition of weakly switched non-blocking system. We say that a language H is *weakly non-blocking* if we can find a non-empty sublanguage $H_i \subseteq H$ such that the concatenation of H_i , intersected alternatively with the first specification language K_1 and with the second specification language K_2 is in the marked states of the system. The definition of switched non-blocking system follows from the previous definition. A system is *switched non-blocking* if it is weakly non-blocking and if the sublanguage is the entire language itself, i.e., $H_i = H$.

We show that the mutually non-blocking property is included in the switched non-blocking property. And we illustrate our result with an example of protocol conversion problem where the converter (the supervisor) deals with two different protocol specifications that switch between them.

Remerciements

We acknowledge fruitful discussions with Prof. Stephane Lafortune on the approach in this paper.

Bibliographie

- Bourdon, S.E., Lawford, M., and Wonham, W.M., (2005) *Robust nonblocking supervisory control of discrete event systems*, In IEEE Trans. on Automatic Control, vol. 50, N.12 pp. 2015–2021.
- Cassandras, C.G. and Lafortune, S. (2008) *Introduction to Discrete Event Systems*, 2nd Edition, Springer Verlag.
- Fabian, M., and Kumar, R. (1997) *Mutually non-blocking supervisory control of discrete-event systems*, In Proc. of IEEE CDC, San Diego, CA, pp. 2970–2975.
- Fabian, M., and Kumar, R. (2000) "Mutually non-blocking supervisory control of discrete-event systems," In *Automatica*, 36(12) pp. 1863–1869.
- Faraut, G., Pietrac, L., and Niel, E. (2009) *Formal Approach to Multimodal Control Design: Application to Mode Switching*, In IEEE Trans. on Industrial Informatics, vol.5, N.4 pp. 443–453.
- Hopcroft, J.E., and Ullman, J.D. (1979) *Introduction to Automata Theory, Languages, and Computation*, Addison-Wesley, Reading, MA, USA, 1979.
- Kumar, R., Takai, S., Fabian, M., and Ushio, T. (2005) *Maximally Permissive Mutually and Globally Nonblocking Supervision with Application to Switching Control* In *Automatica*, 41(8) pp. 1299–1312.
- Liberzon, D. (2003) *Switching in Systems and Control*, ser. Systems and Control: Foundations and Applications. Boston: Birkhauser.
- Malik, R. and Leduc, R. (2008) *Generalised nonblocking*, in Proc. 9th Int. Workshop on Discrete Event Systems, WODES 2008, Goteborg, Sweden, pp. 340–345.
- Ramadge, P.J., and Wonham, W.M. (1987) *Supervisory control of a class of discrete-event processes* In *SIAM J. Control and Optimization*, vol.25 pp. 206–230.
- Roop, P.S., Girault, A., Sinha, R., and Goessler, G. (2009) *Specification Enforcing Refinement for Convertibility Verification*, Proc. of ACSD 2009, pp. 148–157, IEEE.
- van den Boom, T.J.J., and de Schutter, B. (2006) *Modelling and control of discrete event systems using switching max-plus-linear systems*, In *Control Engineering Practice*, vol. 14 N.10, pp. 1199–1211.